

**CHARACTERIZATION OF SMARANDACHE $\mathbf{M}_1\mathbf{M}_2$ CURVES OF
SPACELIKE BIHARMONIC \mathcal{B} -SLANT HELICES ACCORDING
TO BISHOP FRAME IN $\mathbb{E}(1,1)$**

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ABSTRACT. In this paper, we find parametric equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic \mathcal{B} -slant helices according to Bishop frame in terms of Bishop curvatures in the Lorentzian group of rigid motions $\mathbb{E}(1,1)$. Finally, we construct Bishop equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic \mathcal{B} -slant helices in $\mathbb{E}(1,1)$.

1. INTRODUCTION

A curve of constant slope or general helix is defined by the property that the tangent lines make a constant angle with a fixed direction. A necessary and sufficient condition that a curve to be general helix is that ratio of curvature to torsion be constant. Indeed, a helix is a special case of the general helix. If both curvature and torsion are non-zero constants, it is called a helix or only a W-curve.

On the other hand, the Bishop frame or parallel transport frame is an alternative approach to defining a moving frame that is well defined even when the curve has vanishing second derivative. We can parallel transport an orthonormal frame along a curve simply by parallel transporting each component of the frame.

In this paper, we find parametric equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic \mathcal{B} -slant helices according to Bishop frame in terms of Bishop curvatures in the Lorentzian group of rigid motions $\mathbb{E}(1,1)$. Finally, we construct Bishop equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic \mathcal{B} -slant helices in $\mathbb{E}(1,1)$.

2. PRELIMINARIES

Let $\mathbb{E}(1,1)$ be the group of rigid motions of Euclidean 2-space. This consists of all matrices of the form

$$\begin{pmatrix} \cosh x & \sinh x & y \\ \sinh x & \cosh x & z \\ 0 & 0 & 1 \end{pmatrix}.$$

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Topologically, $\mathbb{E}(1, 1)$ is diffeomorphic to \mathbb{R}^3 under the map

$$\mathbb{E}(1, 1) \longrightarrow \mathbb{R}^3 : \begin{pmatrix} \cosh x & \sinh x & y \\ \sinh x & \cosh x & z \\ 0 & 0 & 1 \end{pmatrix} \longrightarrow (x, y, z),$$

It's Lie algebra has a basis consisting of

$$\mathbf{X}_1 = \frac{\partial}{\partial x}, \quad \mathbf{X}_2 = \cosh x \frac{\partial}{\partial y} + \sinh x \frac{\partial}{\partial z}, \quad \mathbf{X}_3 = \sinh x \frac{\partial}{\partial y} + \cosh x \frac{\partial}{\partial z},$$

for which

$$[\mathbf{X}_1, \mathbf{X}_2] = \mathbf{X}_3, \quad [\mathbf{X}_2, \mathbf{X}_3] = 0, \quad [\mathbf{X}_1, \mathbf{X}_3] = \mathbf{X}_2.$$

Put

$$x^1 = x, \quad x^2 = \frac{1}{2}(y + z), \quad x^3 = \frac{1}{2}(y - z).$$

Then, we get

$$(2.1) \quad \mathbf{X}_1 = \frac{\partial}{\partial x^1}, \quad \mathbf{X}_2 = \frac{1}{2} \left(e^{x^1} \frac{\partial}{\partial x^2} + e^{-x^1} \frac{\partial}{\partial x^3} \right), \quad \mathbf{X}_3 = \frac{1}{2} \left(e^{x^1} \frac{\partial}{\partial x^2} - e^{-x^1} \frac{\partial}{\partial x^3} \right).$$

The bracket relations are

$$[\mathbf{X}_1, \mathbf{X}_2] = \mathbf{X}_3, \quad [\mathbf{X}_2, \mathbf{X}_3] = 0, \quad [\mathbf{X}_1, \mathbf{X}_3] = \mathbf{X}_2.$$

We consider left-invariant Lorentzian metrics which has a pseudo-orthonormal basis $\{\mathbf{X}_1, \mathbf{X}_2, \mathbf{X}_3\}$. We consider left-invariant Lorentzian metric [12], given by

$$g = -(dx^1)^2 + \left(e^{-x^1} dx^2 + e^{x^1} dx^3 \right)^2 + \left(e^{-x^1} dx^2 - e^{x^1} dx^3 \right)^2,$$

where

$$g(\mathbf{X}_1, \mathbf{X}_1) = -1, \quad g(\mathbf{X}_2, \mathbf{X}_2) = g(\mathbf{X}_3, \mathbf{X}_3) = 1.$$

Let coframe of our frame be defined by

$$\theta^1 = dx^1, \quad \theta^2 = e^{-x^1} dx^2 + e^{x^1} dx^3, \quad \theta^3 = e^{-x^1} dx^2 - e^{x^1} dx^3.$$

3. SMARANDACHE $\mathbf{M}_1\mathbf{M}_2$ CURVES OF SPACELIKE BIHARMONIC B-SLANT HELICES IN THE LORENTZIAN GROUP OF RIGID MOTIONS $\mathbb{E}(1, 1)$

Let $\gamma : I \longrightarrow \mathbb{E}(1, 1)$ be a non geodesic spacelike curve on the $\mathbb{E}(1, 1)$ parametrized by arc length. Let $\{\mathbf{T}, \mathbf{N}, \mathbf{B}\}$ be the Frenet frame fields tangent to the $\mathbb{E}(1, 1)$ along γ defined as follows:

\mathbf{T} is the unit vector field γ' tangent to γ , \mathbf{N} is the unit vector field in the direction of $\nabla_{\mathbf{T}}\mathbf{T}$ (normal to γ), and \mathbf{B} is chosen so that $\{\mathbf{T}, \mathbf{N}, \mathbf{B}\}$ is a positively oriented orthonormal basis. Then, we have the following Frenet formulas:

$$(3.1) \quad \begin{aligned} \nabla_{\mathbf{T}}\mathbf{T} &= \kappa\mathbf{N}, \\ \nabla_{\mathbf{T}}\mathbf{N} &= \kappa\mathbf{T} + \tau\mathbf{B}, \\ \nabla_{\mathbf{T}}\mathbf{B} &= \tau\mathbf{N}, \end{aligned}$$

where κ is the curvature of γ and τ is its torsion and

$$\begin{aligned} g(\mathbf{T}, \mathbf{T}) &= 1, \quad g(\mathbf{N}, \mathbf{N}) = -1, \quad g(\mathbf{B}, \mathbf{B}) = 1, \\ g(\mathbf{T}, \mathbf{N}) &= g(\mathbf{T}, \mathbf{B}) = g(\mathbf{N}, \mathbf{B}) = 0. \end{aligned}$$

The Bishop frame or parallel transport frame is an alternative approach to defining a moving frame that is well defined even when the curve has vanishing second derivative. The Bishop frame is expressed as

$$(3.2) \quad \begin{aligned} \nabla_{\mathbf{T}}\mathbf{T} &= k_1\mathbf{M}_1 - k_2\mathbf{M}_2, \\ \nabla_{\mathbf{T}}\mathbf{M}_1 &= k_1\mathbf{T}, \\ \nabla_{\mathbf{T}}\mathbf{M}_2 &= k_2\mathbf{T}, \end{aligned}$$

where

$$\begin{aligned} g(\mathbf{T}, \mathbf{T}) &= 1, \quad g(\mathbf{M}_1, \mathbf{M}_1) = -1, \quad g(\mathbf{M}_2, \mathbf{M}_2) = 1, \\ g(\mathbf{T}, \mathbf{M}_1) &= g(\mathbf{T}, \mathbf{M}_2) = g(\mathbf{M}_1, \mathbf{M}_2) = 0. \end{aligned}$$

Here, we shall call the set $\{\mathbf{T}, \mathbf{M}_1, \mathbf{M}_2\}$ as Bishop trihedra, k_1 and k_2 as Bishop curvatures and $\tau(s) = \psi'(s)$, $\kappa(s) = \sqrt{|k_2^2 - k_1^2|}$. Thus, Bishop curvatures are defined by

$$\begin{aligned} k_1 &= \kappa(s) \sinh \psi(s), \\ k_2 &= \kappa(s) \cosh \psi(s). \end{aligned}$$

With respect to the orthonormal basis $\{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$ we can write

$$(3.3) \quad \begin{aligned} \mathbf{T} &= T^1\mathbf{e}_1 + T^2\mathbf{e}_2 + T^3\mathbf{e}_3, \\ \mathbf{M}_1 &= M_1^1\mathbf{e}_1 + M_1^2\mathbf{e}_2 + M_1^3\mathbf{e}_3, \\ \mathbf{M}_2 &= M_2^1\mathbf{e}_1 + M_2^2\mathbf{e}_2 + M_2^3\mathbf{e}_3. \end{aligned}$$

Definition 3.1. Let $\gamma : I \rightarrow \mathbb{E}(1,1)$ be a unit speed regular curve in the Lorentzian group of rigid motions $\mathbb{E}(1,1)$. and $\{\mathbf{T}, \mathbf{M}_1, \mathbf{M}_2\}$ be its moving Bishop frame. Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves are defined by

$$(3.4) \quad \gamma_{\mathbf{M}_1\mathbf{M}_2} = \frac{1}{|k_1 + k_2|} (\mathbf{M}_1 + \mathbf{M}_2).$$

Definition 3.2. [7], A regular spacelike curve $\gamma : I \rightarrow \mathbb{E}(1,1)$ is called a \mathcal{B} -slant helix provided the timelike unit vector \mathbf{M}_1 of the curve γ has constant angle θ with some fixed timelike unit vector u , that is

$$g(\mathbf{M}_1(s), u) = \cosh \wp \text{ for all } s \in I.$$

Lemma 3.3. [7], Let $\gamma : I \rightarrow \mathbb{E}(1,1)$ be a unit speed spacelike curve with non-zero natural curvatures. Then γ is a \mathcal{B} -slant helix if and only if

$$(3.5) \quad \frac{k_1}{k_2} = \tanh \wp.$$

Theorem 3.4. Let $\gamma : I \rightarrow \mathbb{E}(1,1)$ is a non geodesic spacelike biharmonic \mathcal{B} -slant helix in the Lorentzian group of rigid motions $\mathbb{E}(1,1)$. Then, the parametric

equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic slant helix are

$$(3.6) \quad \begin{aligned} \gamma_{\mathbf{M}_1\mathbf{M}_2}(s) &= \mathfrak{C}(\cosh \varphi)\mathbf{X}_1 \\ &+ \mathfrak{C}(\sinh \varphi \cos [D_1s + D_2] - \sin [D_1s + D_2])\mathbf{X}_2 \\ &+ \mathfrak{C}(\sinh \varphi \sin [D_1s + D_2] + \cos [D_1s + D_2])\mathbf{X}_3, \end{aligned}$$

where D_1, D_2 are constants of integration and

$$\mathfrak{C} = \frac{1}{|k_1 + k_2|}.$$

Proof. Assume that γ is a non geodesic spacelike biharmonic \mathcal{B} -slant helix according to Bishop frame.

Hence, from Definition 3.2, we obtain

$$(3.7) \quad \mathbf{M}_1 = \cosh \varphi \mathbf{X}_1 + \sinh \varphi \cos [D_1s + D_2] \mathbf{X}_2 + \sinh \varphi \sin [D_1s + D_2] \mathbf{X}_3.$$

Using (2.1) in (3.7), we may be written as

$$(3.8) \quad \mathbf{M}_2 = -\sin [D_1s + D_2] \mathbf{X}_2 + \cos [D_1s + D_2] \mathbf{X}_3.$$

Substituting (3.7) and (3.8) in (3.4) we have (3.6), which completes the proof.

Then, we obtain the following corollary.

Corollary 3.5. *Let $\gamma : I \longrightarrow \mathbb{E}(1, 1)$ is a non geodesic spacelike biharmonic \mathcal{B} -slant helix in the Lorentzian group of rigid motions $\mathbb{E}(1, 1)$. Then, the parametric equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic slant helix are*

$$(3.9) \quad \begin{aligned} x_{\mathbf{M}_1\mathbf{M}_2}^1(s) &= \mathfrak{C}(\cosh \varphi), \\ x_{\mathbf{M}_1\mathbf{M}_2}^2(s) &= \frac{\mathfrak{C}}{2} e^{\frac{\cosh \varphi}{|k_1+k_2|}} ((\sinh \varphi) \cos [D_1s + D_2] - \sin [D_1s + D_2]) \\ &+ \frac{\mathfrak{C}}{2} e^{\frac{\cosh \varphi}{|k_1+k_2|}} ((\sinh \varphi) \sin [D_1s + D_2] + \cos [D_1s + D_2]), \\ x_{\mathbf{M}_1\mathbf{M}_2}^3(s) &= \frac{\mathfrak{C}}{2} e^{-\frac{\cosh \varphi}{|k_1+k_2|}} ((\sinh \varphi) \cos [D_1s + D_2] - \sin [D_1s + D_2]) \\ &- \frac{\mathfrak{C}}{2} e^{-\frac{\cosh \varphi}{|k_1+k_2|}} ((\sinh \varphi) \sin [D_1s + D_2] + \cos [D_1s + D_2]), \end{aligned}$$

where D_1, D_2 are constants of integration and

$$\mathfrak{C} = \frac{1}{|k_1 + k_2|}.$$

Proof. Substituting (2.1) to (3.6), we have (3.9) as desired.

We may use Mathematica in Corollary 3.5, yields

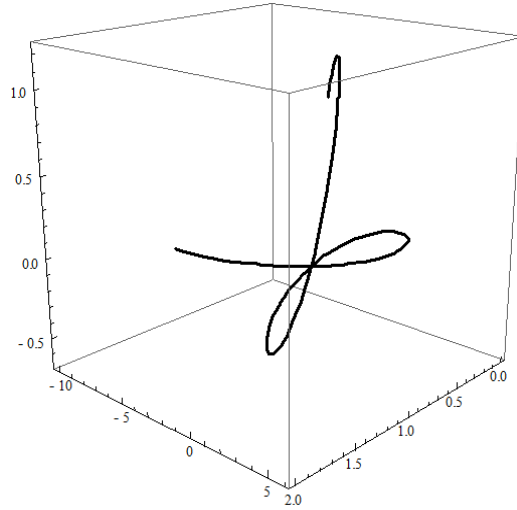


Figure 1.

4. BISHOP EQUATIONS OF SMARANDACHE $\mathbf{M}_1\mathbf{M}_2$ CURVES OF SPACELIKE BIHARMONIC \mathcal{B} -SLANT HELICES IN THE $\mathbb{E}(1, 1)$

In this section, we shall call the set $\{\mathbf{T}^{\mathfrak{B}}, \mathbf{M}_1^{\mathfrak{B}}, \mathbf{M}_2^{\mathfrak{B}}\}$ as Bishop trihedra, $k_1^{\mathfrak{B}}$ and $k_2^{\mathfrak{B}}$ as Bishop curvatures of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curve.

We can now state the main result of the paper.

Theorem 4.1. *Let $\gamma : I \rightarrow \mathbb{E}(1, 1)$ is a non geodesic spacelike biharmonic \mathcal{B} -slant helix in the Lorentzian group of rigid motions $\mathbb{E}(1, 1)$. Then, the Bishop equations of Smarandache $\mathbf{M}_1\mathbf{M}_2$ curves of spacelike biharmonic \mathcal{B} -slant helix are*

$$\begin{aligned}
 \nabla_{\mathbf{T}^{\mathfrak{B}}} \mathbf{T}^{\mathfrak{B}} &= \mathfrak{C}[(k_1 + k_2) k_1 \cosh \varphi] \mathbf{X}_1 \\
 &+ \mathfrak{C}[(k_1 + k_2) k_1 \sinh \varphi \cos [D_1 s + D_2] - (k_1 + k_2) k_2 \sin [D_1 s + D_2]] \mathbf{X}_2 \\
 &+ \mathfrak{C}[(k_1 + k_2) k_1 \sinh \varphi \sin [D_1 s + D_2] + (k_1 + k_2) k_2 \cos [D_1 s + D_2]] \mathbf{X}_3, \\
 \nabla_{\mathbf{T}^{\mathfrak{B}}} \mathbf{M}_1^{\mathfrak{B}} &= k_1^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \sinh \varphi] \mathbf{X}_1 \\
 &+ k_1^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \cos [D_1 s + D_2]] \mathbf{X}_2 \\
 &+ k_1^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \sin [D_1 s + D_2]] \mathbf{X}_3, \\
 \nabla_{\mathbf{T}^{\mathfrak{B}}} \mathbf{M}_2^{\mathfrak{B}} &= k_2^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \sinh \varphi] \mathbf{X}_1 \\
 &+ k_2^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \cos [D_1 s + D_2]] \mathbf{X}_2 \\
 &+ k_2^{\mathfrak{B}} \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \sin [D_1 s + D_2]] \mathbf{X}_3,
 \end{aligned}
 \tag{4.1}$$

where $k_1^{\mathfrak{B}}, k_2^{\mathfrak{B}}$ are Bishop curvatures of $\gamma_{\mathbf{M}_1\mathbf{M}_2}$, D_1, D_2 are constants of integration and

$$\mathfrak{C} = \frac{1}{|k_1 + k_2|}.$$

Proof. Assume that γ is a non geodesic spacelike biharmonic \mathcal{B} -slant helix and its Smarandache $\mathbf{M}_1\mathbf{M}_2$ curve is $\gamma_{\mathbf{M}_1\mathbf{M}_2}$.

From (3.4), we have

$$(4.2) \quad \mathbf{T}^{\mathfrak{B}} = \mathfrak{C}((k_1 + k_2) \mathbf{T}),$$

where $\mathfrak{C} = \frac{1}{|k_1 + k_2|}$.

On the other hand, a straightforward computation gives

$$(4.3) \quad \begin{aligned} \mathbf{T}^{\mathfrak{B}} &= \mathfrak{C}[-(k_1 + k_2) \sinh \varphi] \mathbf{X}_1 \\ &+ \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \cos [D_1 s + D_2]] \mathbf{X}_2 \\ &+ \mathfrak{C}[-(k_1 + k_2) \cosh \varphi \sin [D_1 s + D_2]] \mathbf{X}_3. \end{aligned}$$

From (2.1), we have

$$\begin{aligned} \nabla_{\mathbf{T}^{\mathfrak{B}}} \mathbf{T}^{\mathfrak{B}} &= \mathfrak{C}[(k_1 + k_2) k_1 \cosh \varphi] \mathbf{X}_1 \\ &+ \mathfrak{C}[(k_1 + k_2) k_1 \sinh \varphi \cos [D_1 s + D_2] - (k_1 + k_2) k_2 \sin [D_1 s + D_2]] \mathbf{X}_2 \\ &+ \mathfrak{C}[(k_1 + k_2) k_1 \sinh \varphi \sin [D_1 s + D_2] + (k_1 + k_2) k_2 \cos [D_1 s + D_2]] \mathbf{X}_3. \end{aligned}$$

Considering Eqs.(3.2) and (3.3), we obtain the theorem. This concludes the proof of theorem.

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