HORIZONTAL GEODESICS IN LORENTZIAN HEISENBERG GROUP HEIS³

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ABSTRACT. In this paper, we study different geodesic lines on the Lorentzian Heis³. We consider the Lorentzian left invariant metric and use some results of Levi-Civita connection and curvature tensor to present solution of equations for geodesic lines in Lorentzian Heis³. Furthermore it is obtained equations of geodesic lines with respect to the left invariant Lorentzian metric of the Heis³. We characterize horizontal geodesic curves in Lorentzian Heis³ and prove that there exist no null horizontal geodesic curves in Lorentzian Heis³.

1. INTRODUCTION

Rahmani (see [4]) described one motivation for our study that there are three classes of left invariant Lorentzian metrics on the Heis³.

In (see [2]) V. Marenich used Heisenberg left invariant metric and obtained geodesic lines in Heis³.

Returning to geometry, we note that the Heis³ serves also as a contact manifold. This is the odd dimension analog for a symplectic structure. The 1-form $\omega^1 = dt + xdy$, which anihilates e_1 and e_2 is a contact form, i.e. $\omega^1 \wedge d\omega^1$ never vanishes. The 2-form $\Omega = d\omega^1 = dx \wedge dy$ is a symplectic form on the distribution generated by e_1 and e_2 . It can be considered also as a magnetic field. Then the Maxwell's equation can be written as $d\Omega = 0$.

In this paper, we study different geodesic lines on the Lorentzian Heis³. We consider the Lorentzian left invariant metric and use some results of Levi-Civita connection and curvature tensor to present solution of equations for geodesic lines in Lorentzian Heis³. Furthermore it is obtained equations of geodesic lines with respect to the left invariant Lorentzian metric of the Heis³. We characterize horizontal geodesic curves in Lorentzian Heis³ and prove that there exist no null horizontal geodesic curves in Lorentzian Heis³.

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2. Lorentzian Heisenberg Group HEIS³

This group is formed by all matrices of the form

$$Heis^{3} = \left\{ \left(\begin{array}{ccc} 1 & x & t \\ 0 & 1 & y \\ 0 & 0 & 1 \end{array} \right) : x, y, t \in \mathbb{R} \right\}$$

with the group multiplication induced by the standard matrix product.

The Lorentzian Heis³ can be seen as the space \mathbb{R}^3 endowed with multiplication

$$(\overline{x},\overline{y},\overline{t})(x,y,t) = (\overline{x}+x,\overline{y}+y,\overline{t}+t-\overline{x}y+x\overline{y}).$$

The orthonormal basis

$$E_1 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad E_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad E_3 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

of tangent space at the identity, determines on Heis^3 a left invariant Lorentzian metric

(2.1)
$$ds^{2} = (\omega^{1})^{2} + (\omega^{2})^{2} - (\omega^{3})^{2}$$

where

$$\omega^1 = dt + x dy, \qquad \omega^2 = dy, \qquad \omega^3 = dx$$

is the left invariant orthonormal coframe associated with the orthonormal left invariant frame,

(2.2)
$$e_1 = \frac{\partial}{\partial t}, \quad e_2 = \frac{\partial}{\partial y} - x \frac{\partial}{\partial t}, \quad e_3 = \frac{\partial}{\partial x}.$$

Now let C_{ij}^k be the structure's constants of the Lie algebra g of G (see [5]), that is

$$[e_i, e_j] = C_{ij}^k e_k.$$

The corresponding Lie brackets are

$$[e_2, e_3] = 2e_1, \qquad [e_1, e_3] = [e_1, e_2] = 0$$

The Coshul formula for the Levi–Civita connection is:

$$2g(\nabla_{e_i}e_j, e_k) = C_{ij}^k - C_{jk}^i + C_{ki}^j := L_{ij}^k$$

where the non zero L_{ij}^k 's are

(2.3)
$$L_{12}^3 = 2, \ L_{21}^3 = 2, \ L_{13}^2 = 2, \ L_{31}^2 = 2, \ L_{23}^1 = 2, \ L_{32}^1 = 2.$$

The element zero 0 = (0, 0, 0) is the unit of this group strucure and the inverse element for (z, t) is $(z, t)^{-1} = (-z, -t)$. Let a = (z, t), b = (w, s). The commutator of the elements $a, b \in Heis^3$ is equal to

$$[a, b] = aba^{-1}b^{-1}$$

= (z, t) (w, s) (-z, -t) (-w, -s)
= (z + w - z + w, t + s - t - s + \alpha) = (0, \alpha)

where $\alpha \neq 0$ in general. Which shows that Heis³ is not abelian. On the other hand for any $a, b, c \in Heis^3$, their double commutator is

$$[[a,b],c] = (0,0)$$

Heisenberg group plays an important role in many branches of mathematics such as representation theory, harmonic analysis, PDEs or even quantum mechanic. Heis³ has a rich geometric structure. In fact its group of isometries is of dimension 4, which is the maximal possible dimension for a non-constant curvature metric on a 3-manifold. Also, from the algebraic point of view, Heis³ is a 2-step nilpotent Lie group, i.e. "almost Abelian".

3. Horizontal Geodesics in the Lorentzian HEIS³

Consider a nonintegrable 2-dimensional distribution $x \longrightarrow \mathcal{H}_x$ defined as $\mathcal{H} = \ker \omega$, where ω is a 1-form on Heis³. The distribution \mathcal{H} is called the horizontal distribution. A curve $s \longrightarrow c(s) = (x(s), y(s), t(s))$ is called horizontal curve if $c'(s) \in \mathcal{H}_{c(s)}$, for every s (see [6]).

Theorem 3.1. Spacelike geodesic lines issuing from 0 in the Lorentzian $Heis^3$ is solution following differential equation system:

(3.1)
$$x'(s) = \sqrt{1 - \xi^{2}} \sinh(2\xi s + \phi),$$
$$y'(s) = \sqrt{1 - \xi^{2}} \cosh(2\xi s + \phi),$$
$$t'(s) = \xi - x(s)\sqrt{1 - \xi^{2}} \cosh(2\xi s + \phi).$$

Proof. Let c(s) be such a geodesics with a natural parameters s and its vector of velocity given by

(3.2)
$$c'(s) = \xi(s) e_1 + \eta(s) e_2 + \rho(s) e_3.$$

Then the equation of a geodesic $\nabla_{c'(s)}c'(s) \equiv 0$ and our table of covariant derivatives (3.2) give

(3.3)
$$\xi'(s) e_1 + (\eta'(s) + 2\xi(s) \rho(s)) e_2 + (\rho'(s) - 2\xi(s) \eta(s)) e_3 = 0.$$

Thus we easily obtain the following equations for coordinates of the velocity of the geodesic c(s) in our left-invariant moving frame

(3.4)
$$\begin{aligned} \xi'(s) &= 0, \\ \eta'(s) + 2\xi(s) \,\rho(s) &= 0, \\ \rho'(s) - 2\xi(s) \,\eta(s) &= 0 \end{aligned}$$

or

(3.5)
$$(\eta (s) + \rho (s))' + 2\xi (s) (\rho (s) - \eta (s)) = 0, (\eta (s) - \rho (s))' + 2\xi (\rho (s) + \eta (s)) = 0.$$

Since $c: I \longrightarrow Heis^3$ is spacelike curve, we have

(3.6)
$$\xi^{2}(s) + \eta^{2}(s) - \rho^{2}(s) = 1$$

and from (3.4) we could take

$$\xi = const.$$

where $|\xi| \leq 1$. From (3.6) we could find that,

(3.7)
$$\begin{aligned} \xi &= const.\\ \eta \left(s \right) &= r \cosh \left(2\xi s + \phi \right),\\ \rho \left(s \right) &= r \sinh \left(2\xi s + \phi \right) \end{aligned}$$

where $r = \sqrt{\eta^2(s) - \rho^2(s)}$.

To find equations for geodesic c(s) = (x(s), y(s), z(s)) issuing from 0, we note that if

(3.8)
$$c'(s) = \xi(s) e_1 + \eta(s) e_2 + \rho(s) e_3$$

and our left-invariant vector fields are

$$e_1 = \frac{\partial}{\partial z}, \quad e_2 = \frac{\partial}{\partial y} - x \frac{\partial}{\partial z}, \quad e_3 = \frac{\partial}{\partial x}.$$

Then we easily have (3.1).

Corollary 3.2. Let $\gamma : I \longrightarrow Heis^3$ be a unit speed spacelike geodesic curve. Then, the parametric equation of spacelike geodesic are

(3.9)

$$x(s) = \frac{\sqrt{1-\xi^2}}{2\xi} \cosh(2\xi s + \phi) + c_1,$$

$$y(s) = \frac{\sqrt{1-\xi^2}}{2\xi} \sinh(2\xi s + \phi) + c_2,$$

$$t(s) = \left(\xi - \frac{1-\xi^2}{4\xi}\right)s - \frac{1-\xi^2}{8\xi^2}\sinh 2\left(2\xi s + \phi\right)$$

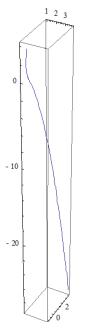
$$- \frac{c_1\sqrt{1-\xi^2}}{2\xi}\sinh(2\xi s + \phi),$$

where c_1, c_2, c_3 are constants of integration.

Next, we apply Corollary 3.2.

Example 3.3. Let us consider parametric equation of spacelike geodesic lines with $\xi = \frac{1}{2}$, $\phi = 0$ and $c_1 = c_2 = c_3 = 1$. Then, we can draw spacelike geodesic

lines with helping the programme of Mathematica as follow



Theorem 3.4. If $c: I \longrightarrow Heis^3$ spacelike horizontal geodesic lines issuing from zero 0, then satisfy to the following equations:

(3.10)

$$x(s) = s \sinh \phi + a,$$

$$y(s) = s \cosh \phi + b,$$

$$t(s) = \frac{s^2}{2} \sinh \phi \cosh \phi + a \cosh \phi s + c,$$

where a, b, c are constants of integration.

Proof. Let c(s) be a horizontal geodesics. From horizontal curve equation, we get

(3.11)
$$w(c'(s)) = \xi = 0$$

If we use (3.11) in (3.7) and some calculations, we have

(3.12)
$$\begin{aligned} \xi &= 0\\ \eta \left(s \right) &= \cosh \phi,\\ \rho \left(s \right) &= \sinh \phi \end{aligned}$$

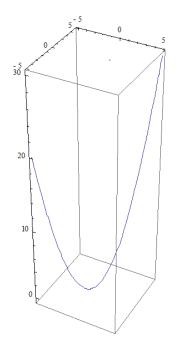
and (3.12) in (3.8) we obtain

$$x'(s) = \sinh \phi$$
$$y'(s) = \cosh \phi$$
$$t'(s) = x(s) \cosh \phi$$

The integration is immediate and yelds (3.10).

Next, we apply Theorem 3.4.

Example 3.5. Let us consider parametric equation of spacelike horizontal geodesic lines with a = b = c = 1. Then, we can draw spacelike horizontal geodesic with helping the programme of Mathematica as follow



Lemma 3.6. Timelike geodesic lines issuing from 0 in the Lorentzian $Heis^3$ is solution following differential equation system;

(3.13)
$$x'(s) = \sqrt{1 + \xi^{2}} \cosh(2\xi s + \phi),$$
$$y'(s) = \sqrt{1 + \xi^{2}} \sinh(2\xi s + \phi),$$
$$t'(s) = \xi - x(s)\sqrt{1 + \xi^{2}} \sinh(2\xi s + \phi).$$

Corollary 3.7. Let $\gamma : I \longrightarrow Heis^3$ be a unit speed geodesic curve. Then, the parametric equation of spacelike geodesic are

(3.14)

$$x(s) = \frac{\sqrt{1+\xi^2}}{2\xi} \sinh(2\xi s + \phi) + c_1,$$

$$y(s) = \frac{\sqrt{1+\xi^2}}{2\xi} \cosh(2\xi s + \phi) + c_2,$$

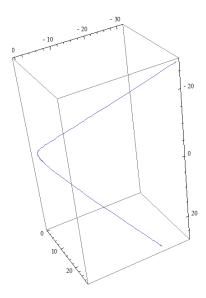
$$t(s) = \left(\xi - \frac{1+\xi^2}{4\xi}\right)s - \frac{1+\xi^2}{8\xi^2}\sinh 2\left(2\xi s + \phi\right)$$

$$- \frac{c_1\sqrt{1+\xi^2}}{2\xi}\cosh\left(2\xi s + \phi\right),$$

where c_1, c_2, c_3 are constants of integration.

Next, we apply Corollary 3.7.

Example 3.8. Let us consider parametric equation of spacelike geodesic lines with $\xi = 1$, $\phi = 0$ and $c_1 = c_2 = c_3 = 1$. Then, we can draw spacelike geodesic lines with helping the programme of Mathematica as follow



Corollary 3.9. If $c : I \longrightarrow Heis^3$ timelike horizontal geodesic lines issuing from zero 0, then satisfy to the following equations:

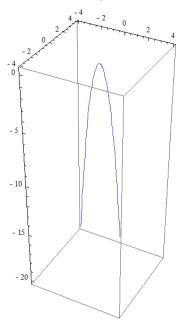
(3.13)
$$x(s) = s \cosh \phi + a,$$
$$y(s) = s \sinh \phi + b,$$
$$t(s) = \frac{s^2}{2} \sinh \phi \cosh \phi + a \sinh \phi s + c,$$

where a, b, c are constants of integration.

Next, we apply Corollary 3.9.

Example 3.10. Let us consider parametric equation of timelike geodesic lines with a = b = c = 1. Then, we can draw timelike horizontal geodesic lines with

helping the programme of Mathematica as follow



Theorem 3.11. There exists no null horizontal geodesic in Lorentzian Heis³.

Proof. We prove that by contradiction. Let us assume that $c: I \longrightarrow Heis^3$ is null horizontal geodesic curve parametrized by arc length. Then, null geodesic lines issuing from 0 in the Lorentzian $Heis^3$ is solution following differential equation system;

(3.14)
$$x'(s) = |\xi| \sinh(2\xi s + \phi)$$
$$y'(s) = |\xi| \cosh(2\xi s + \phi)$$
$$t'(s) = \xi - x(s) |\xi| \cosh(2\xi s + \phi)$$

Substitute equations (3.11) into (3.16) we have

(3.15)
$$\eta(s) = 0, \ \rho(s) = 0$$

From (3.8) we get c'(s) = 0. This contradiction proves the claim.

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