CHARACTERIZATION OF RICCI TENSOR IN THE LORENTZIAN HEISENBERG GROUP HEIS³

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ABSTRACT. In this paper, we consider the Lorentzian Heisenberg left-invariant metric and use some results on Levi-Civita connection. We characterize the components of the Ricci tensor.

1. INTRODUCTION

Heisenberg group and their subelliptic Laplacians are at the cross-roads of many domains of analysis and geometry: Nilpotent Lie group theory, hypoelliptic second order partial differential equations, strictly pseudoconvex domains in complex analysis, probability theory of degenerate diffusion processes, sub-Riemannian geometry, control theory and semiclassical analysis of quantum mechanics, [2,3,11].

On the other hand, Heisenberg group has a rich geometric structure. In fact its group of isometries is of dimension 4, which is the maximal possible dimension for a non-constant curvature metric on a 3-manifold. Also, from the algebraic point of view, Heis³ is a 2-step nilpotent Lie group, i.e. "almost Abelian".

In this paper, we consider the Lorentzian Heisenberg left-invariant metric and use some results on Levi-Civita connection. We characterize the components of the Ricci tensor.

2. RICCI TENSOR IN THE LORENTZIAN HEISENBERG GROUP HEIS³

Heisenberg group plays an important role in many branches of mathematics such as representation theory, harmonic analysis, PDE's or even quantum mechanic. Heis³ has a rich geometric structure. In fact its group of isometries is of dimension 4, which is the maximal possible dimension for a non-constant curvature metric on a 3-manifold. Also, from the algebraic point of view, Heis³ is a 2-step nilpotent Lie group, i.e. "almost Abelian".

This group is formed by all matrices of the form

$$Heis^{3} = \left\{ \left(\begin{array}{ccc} 1 & x & z \\ 0 & 1 & y \\ 0 & 0 & 1 \end{array} \right) : x, y, z \in \mathbb{R} \right\},\$$

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with the group multiplication induced by the standard matrix product.

The Lorentzian Heisenberg group Heis^3 can be seen as the space \mathbb{R}^3 endowed with multiplication

$$(\overline{x},\overline{y},\overline{z})(x,y,z) = (\overline{x}+x,\overline{y}+y,\overline{z}+z-\overline{x}y+x\overline{y}).$$

The orthonormal basis

$$\mathbf{E}_1 = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad \mathbf{E}_2 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}, \quad \mathbf{E}_3 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

of tangent space at the identity, determines on Heis^3 a left-invariant Lorentzian metric

(2.1)
$$ds^{2} = (\omega^{1})^{2} + (\omega^{2})^{2} - (\omega^{3})^{2},$$

where

$$\omega^1 = dz + xdy, \qquad \omega^2 = dy, \qquad \omega^3 = dx$$

is the left-invariant orthonormal coframe associated with the orthonormal left-invariant frame,

(2.2)
$$\mathbf{e}_1 = \frac{\partial}{\partial z}, \quad \mathbf{e}_2 = \frac{\partial}{\partial y} - x \frac{\partial}{\partial z}, \quad \mathbf{e}_3 = \frac{\partial}{\partial x}.$$

The corresponding Lie brackets are

$$[\mathbf{e}_2, \mathbf{e}_3] = 2\mathbf{e}_1, \qquad [\mathbf{e}_1, \mathbf{e}_3] = [\mathbf{e}_1, \mathbf{e}_2] = 0.$$

Now let C_{ij}^k be the structure's constants of the Lie algebra g of G [14] that is,

$$\left[\mathbf{e}_i, \mathbf{e}_j\right] = C_{ij}^k \mathbf{e}_k$$

The Coshul formula for the Levi–Civita connection is:

$$2g(\nabla_{\mathbf{e}_i}\mathbf{e}_j,\mathbf{e}_k) = C_{ij}^k - C_{jk}^i + C_{ki}^j := L_{ij}^k,$$

where the non zero L_{ij}^k 's are

(2.3)
$$L_{12}^3 = 1, \ L_{21}^3 = 1, \ L_{13}^2 = 1, \ L_{31}^2 = 1, \ L_{23}^1 = 1, \ L_{32}^1 = 1.$$

The vector fields (2.2) define a unique Riemannian metric g such that

$$g(\mathbf{e}_1, \mathbf{e}_1) = \lambda, \quad g(\mathbf{e}_2, \mathbf{e}_2) = 1, \quad g(\mathbf{e}_3, \mathbf{e}_3) = -1, \quad \lambda > 0.$$

The coefficients are given by

(2.4)
$$g_{ij}^{(\lambda)} = \begin{pmatrix} -1 & 0 & 0\\ 0 & 1 + \lambda x^2 & \lambda x\\ 0 & \lambda x & \lambda \end{pmatrix}.$$

To avoid confusion we shall denote the above metric by $g^{(\lambda)}$.

Theorem 2.1. If $R_{ij}^{(\lambda)}$ are the components of the Ricci tensor with respect to the metric $g_{ij}^{(\lambda)}$ on Heis³, then

$$R_{11} = -2\lambda, \quad R_{22} = 2\lambda, \quad R_{33} = -2\lambda^2.$$

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Proof. A computation shows that the non-zero components of the 4-covariant Riemann tensor of curvature are

$$\begin{aligned} R_{2323} &= \lambda^2, \quad R_{1313} = -\lambda^2, \\ R_{1213} &= x\lambda^2, \quad R_{1212} = 3\lambda + x^2\lambda^2 \end{aligned}$$

Using the contraction formula

$$R_{ij} = \sum_{k,l} R_{ijkl} \left(g^{\lambda} \right)^{kl},$$

where

$$(g^{\lambda})^{kl} = \begin{pmatrix} -1 & 0 & 0\\ 0 & 1 & -\lambda x\\ 0 & -x & \frac{1}{\lambda} + x^2 \end{pmatrix}.$$

The non-zero components of the Ricci tensor are

$$R_{11} = -2\lambda, \quad R_{22} = 2\lambda, \quad R_{33} = -2\lambda^2.$$

This proves the claim.

We start with the properties of the Levi-Civita connection on Heis³. For each metric g^{λ} one has a natural Levi-Civita connection ∇^{λ} defined by

(2.5)
$$\nabla_{\partial_i}^{\lambda} \partial_j = \Gamma_{ij}^k(\lambda) \partial_k,$$

where the Christoffel symbols are defined by the metric (2.4). They depend linearly on λ and are given by

(2.6)
$$\begin{array}{ccc} \Gamma_{12}^2 = \lambda x, & \Gamma_{12}^3 = -\lambda x^2, & \Gamma_{13}^2 = \lambda, \\ \Gamma_{13}^3 = -\lambda x & \Gamma_{23}^1 = \lambda, & \Gamma_{22}^1 = 2\lambda x. \end{array}$$

Theorem 2.2. For every $\lambda > 0$ we obtain

$$\begin{split} \nabla^{\lambda}_{\partial_{1}}\partial_{2} &= \lambda x \mathbf{e}_{2}, \ \nabla^{\lambda}_{\partial_{2}}\partial_{3} = \nabla^{\lambda}_{\partial_{3}}\partial_{2} = \lambda \mathbf{e}_{3}, \\ \nabla^{\lambda}_{\partial_{2}}\partial_{1} &= \mathbf{e}_{1} + \lambda x \mathbf{e}_{2}, \ \nabla^{\lambda}_{\partial_{1}}\partial_{3} = \nabla^{\lambda}_{\partial_{3}}\partial_{1} = \lambda \mathbf{e}_{2}, \\ \nabla^{\lambda}_{\partial_{1}}\partial_{1} &= 0, \ \nabla^{\lambda}_{\partial_{2}}\partial_{2} = 2\lambda x \mathbf{e}_{3}, \ \nabla^{\lambda}_{\partial_{3}}\partial_{3} = 0. \end{split}$$

Proof. Using (2.6), this proves the claim.

Corollary 2.3. The vector fields \mathbf{e}_1 and \mathbf{e}_3 are geodesic vector fields.

Proof. By Proposition 2.2, we have

$$\nabla_{\mathbf{e}_1}^{\lambda}\mathbf{e}_1 = 0, \quad \nabla_{\mathbf{e}_3}^{\lambda}\mathbf{e}_3 = 0.$$

The corollary is proved.

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